## What Is Claimed Is:

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1. A method for measuring an absolute steering angle  $\Phi$  of a steering shaft for a vehicle using a first rotatable body that rotates together with the steering shaft of the vehicle at a predetermined rotation ratio, the method comprising the steps of:

obtaining a  $\Psi_{M}'$  value by measuring a relative rotational angle  $\Psi'$  of the first rotatable body by means of a first angle sensor whose measurement range is  $\Omega$ ;

obtaining a present value for a frequency i-value of the first rotatable body by comparing the present  $\Psi_{M}$ ' value to a previous  $\Psi_{M}$ ' value; and

obtaining a present value for a absolute steering angle  $\Phi 1$  of the steering shaft from a present value for an absolute rotational angle  $\Psi$  of the first rotatable body by using the  $\Psi_{M}'$  value and the present i-value.

2. The method according to claim 1, comprising the steps of:

obtaining a  $\theta_{M}$ ' value by measuring a relative rotational angle  $\theta$ ' of the second rotatable body, which is rotating together with a steering shaft at a predetermined rotation ratio, by means of a second angle sensor whose measurement range is  $\Omega$ ;

obtaining a present value for a frequency j-value of the second rotatable body by comparing a present  $\theta_{M}$  value to a previous  $\theta_{M}$  value; and

obtaining a present value for the absolute steering angle  $\Phi 2$  of the steering shaft from a present value for an absolute rotational angle  $\theta$  of the second rotatable body by using the  $\theta_{M}'$  value and the present j-value; and

taking a mean value of the  $\Phi$ 1 and the  $\Phi$ 2.